

Learning with little mixing

I. Ziemann (KTH) and Stephen Tu (Google)

(Appeared at NeurIPS'22)

Overview

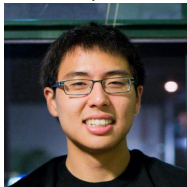
In collaboration

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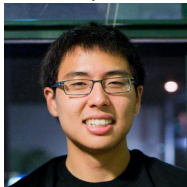
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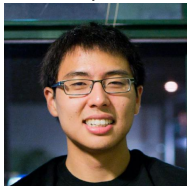
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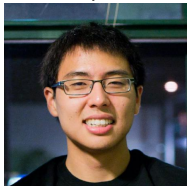


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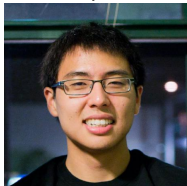


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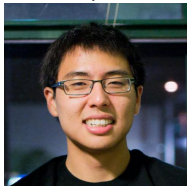


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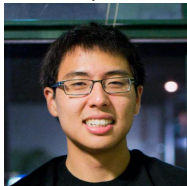
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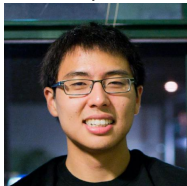
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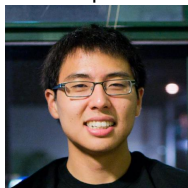
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Lower isometry

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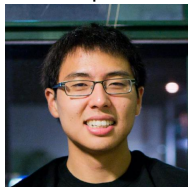
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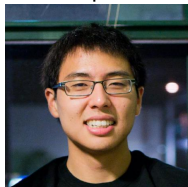
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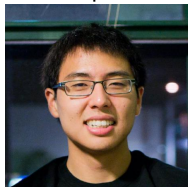
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
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(An open problem )

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What are the key properties dynamical (or control) systems need to possess for learning to be feasible?

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Today: discuss the above question in terms of **nonlinear** time-series

Q: What is the effect of mixing on the rate of convergence of the ERM?

Tsiamis et al. [2022b]: Recent survey in the linear setting
<https://arxiv.org/abs/2209.05423>

Statistical Learning Theory for Control

A FINITE SAMPLE PERSPECTIVE

Anastasios Tsiamis*, Ingvar Ziemann*, Nikolai Matni, and George J. Pappas

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N. Matni (nmatni@seas.upenn.edu) and G. J. Pappas (pappasg@seas.upenn.edu) are with the Dept. of Electrical and Systems Engineering, University of Pennsylvania, Philadelphia, USA.

*Both authors contributed equally.

Lit Review: Learning without mixing in LDS

For linear dynamical systems

$$X_{t+1} = A_* X_t + W_t \quad \Gamma_k \triangleq \sum_{t=0}^k A^t (A^t)^T \quad \rho(A_*) \leq 1 \quad (1)$$

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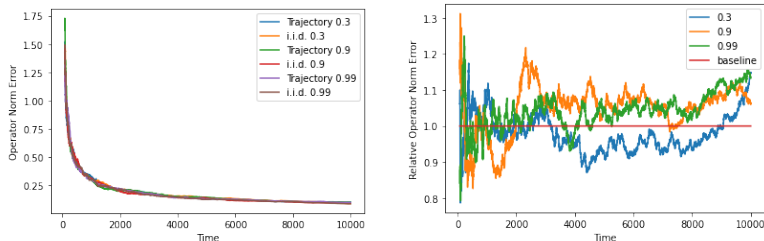


Figure: The spectral radius of the matrix A_* has (almost) no impact on the rate of convergence; $\rho(A_*) \in \{0.3, 0.9, 0.99\}$ and $\sigma_{\min}(A_*) \approx 0$

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two types of rates: iid rate or iid rate \times dependency deflation

Q: when do we get the iid rate?

Problem Formulation

Interested in nonlinear time-series / dynamical system ($Y_t = X_{t+1}$)

$$\underset{Y \subset \mathbb{R}^{d_Y}}{\overset{m}{Y_t}} = f_{\star} \left(\underset{X \subset \mathbb{R}^{d_X}}{\overset{m}{X_t}} \right) + \underset{Y \subset \mathbb{R}^{d_Y}}{\overset{m}{W_t}} \quad f_{\star} \in \mathcal{F} \quad (3)$$

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Interested in the performance of ERM:

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in terms of square-loss excess risk:

$$\|f - f_\star\|_{L^2}^2 \triangleq \frac{1}{T} \sum_{t=0}^{T-1} \mathbf{E} \|f(X_t) - f_\star(X_t)\|_2^2 \quad (f \in \mathcal{F})$$

Contribution

Study ERM under two assumptions

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A1. Trajectory Hypercontractivity (identifiability/small-ball)

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Study ERM under two assumptions

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A2. Mixing

Main result: Informally, under A1-A2, ERM \hat{f} satisfies:

$$\mathbf{E} \|\hat{f} - f_{\star}\|_{L^2}^2 \lesssim \left(\frac{\text{dimensional factors} \times \sigma_W^2}{T} \right)^{\text{comp}(\mathcal{F})} \\ + \text{higher order } o(t_{\text{mix}}/T^{\text{comp}(\mathcal{F})}) \text{ terms} \quad (4)$$

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\Rightarrow we match the iid rate

Contribution

Study ERM under two assumptions

A1. Trajectory Hypercontractivity (identifiability/small-ball)

A2. Mixing

Main result: Informally, under A1-A2, ERM \hat{f} satisfies:

$$\mathbf{E} \|\hat{f} - f_{\star}\|_{L^2}^2 \lesssim \left(\frac{\text{dimensional factors} \times \sigma_W^2}{T} \right)^{\text{comp}(\mathcal{F})} + \text{higher order } o(t_{\text{mix}}/T^{\text{comp}(\mathcal{F})}) \text{ terms} \quad (4)$$

$\text{comp}(\mathcal{F})$: (inverse) measure of complexity

Takeaway: after a burn-in, slow mixing does not impede convergence for a large class of problems

\Rightarrow we match the iid rate

Examples: LDS, GLM, RKHS, finite hyp. classes, ergodic finite state MC

So how do we get there?

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Second, in the LDS setting, can adapt [Mendelson \[2014\]](#) to control

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⇒ Challenge: we also require a nonlinear *lower-isometry* analogue of (6)

High-Level Proof Strategy

First challenge: Prove a high probability lower isometry result

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Quadratic penalization in (8) gives free localization/self-normalization 🟢

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combining (7) and (8): $\frac{1}{T} \sum_{t=0}^{T-1} \mathbf{E} \|\hat{f}(X_t) - f_*(X_t)\|_2^2 \lesssim M_T(\mathcal{F}_*)$

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⇒ know how to control empirical excess risk — need lower iso!

Lower Isometry: Mixing

The following Bernstein-type inequality is key

Theorem (Samson [2000, Theorem 2])

Let $g : X \rightarrow \mathbb{R}$ be non-negative. Then for any $\lambda \geq 0$ we have that:

$$\mathbf{E} \exp \left(-\lambda \sum_{t=0}^{T-1} g(X_t) \right) \leq \exp \left(-\lambda \sum_{t=0}^{T-1} \mathbf{E} g(X_t) + \frac{\lambda^2 \|\Gamma_{\text{dep}}(P_X)\|_{\text{op}}^2 \sum_{t=0}^{T-1} \mathbf{E} g^2(X_t)}{2} \right). \quad (9)$$

where $\|\Gamma_{\text{dep}}(P_X)\|_{\text{op}}$ can be bounded as

$\|\Gamma_{\text{dep}}(P_X)\|_{\text{op}} = O(1)$ if P_X is geo ϕ -mixing

(!) However, $\|\Gamma_{\text{dep}}(P_X)\|_{\text{op}}^2 = o(T)$ is sufficient for us to obtain interesting results

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where $\|\Gamma_{\text{dep}}(P_X)\|_{\text{op}}$ is given by

Definition (Dependency matrix 1, Samson [2000, Section 2])

The *dependency matrix* of a process $X_{0:T-1}$ with distribution P_X is the (upper-triangular) matrix $\Gamma_{\text{dep}}(P_X) = \{\Gamma_{ij}\}_{i,j=0}^{T-1} \in \mathbb{R}^{T \times T}$ defined as follows. Let $\mathcal{X}_{0:i}$ denote the σ -field generated by $\{X_t\}_{t=0}^i$. For indices $i < j$, let

$$\Gamma_{ij} = \sqrt{2 \sup_{A \in \mathcal{X}_{0:i}} \|\mathbf{P}_{X_{j:T-1}}(\cdot | A) - \mathbf{P}_{X_{j:T-1}}\|_{\text{TV}}}. \quad (11)$$

For the remaining indices $i \geq j$, let $\Gamma_{ii} = 1$ and $\Gamma_{ij} = 0$ when $i > j$ (below the diagonal).

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Fix constants $C > 0$ and $\alpha \in [1, 2]$. We say that the tuple (\mathcal{F}, P_X) satisfies the *trajectory (C, α) -hypercontractivity condition* if

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- Ellipsoids in $\ell^2(\mathbb{N})$, i.e., RKHS

Lower Isometry: Sketch

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$$\begin{aligned} & \mathbf{P} \left(\sum_{t=0}^{T-1} \|f(\mathbf{X}_t)\|_2^2 \leq \frac{1}{2} \sum_{t=0}^{T-1} \mathbf{E} \|f(\mathbf{X}_t)\|_2^2 \right) \\ & \leq \inf_{\lambda \geq 0} \mathbf{E} \exp \left(\frac{\lambda}{2} \sum_{t=0}^{T-1} \mathbf{E} \|f(\mathbf{X}_t)\|_2^2 - \lambda \sum_{t=0}^{T-1} \|f(\mathbf{X}_t)\|_2^2 \right) && \text{(Chernoff)} \\ & \leq \inf_{\lambda \geq 0} \exp \left(-\frac{\lambda}{2} \sum_{t=0}^{T-1} \mathbf{E} \|f(\mathbf{X}_t)\|_2^2 + \frac{\lambda^2 \|\Gamma_{\text{dep}}(\mathbf{P}_X)\|_{\text{op}}^2 \sum_{t=0}^{T-1} \mathbf{E} \|f(\mathbf{X}_t)\|_2^4}{2} \right) && \text{(Samson's)} \\ & \leq \exp \left(-\frac{T}{8C \|\Gamma_{\text{dep}}(\mathbf{P}_X)\|_{\text{op}}^2} \times \left(\frac{1}{T} \sum_{t=0}^{T-1} \mathbf{E} \|f(\mathbf{X}_t)\|_2^2 \right)^{2-\alpha} \right), && \text{(hyp. con.)} \end{aligned}$$

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assume star-shaped + use a union bound:

$$\begin{aligned} & \mathbf{P} \left(\sup_{f \in \mathcal{F}_* \setminus \{\|f\|_{L^2} \leq r\}} \left\{ \frac{1}{T} \sum_{t=0}^{T-1} \|f(X_t)\|_2^2 - \mathbf{E} \frac{1}{8T} \sum_{t=0}^{T-1} \|f(X_t)\|_2^2 \right\} \leq 0 \right) \\ & \leq |\mathcal{F}_r| \exp \left(\frac{-Tr^{4-2\alpha}}{8C \|\Gamma_{\text{dep}}(\mathbf{P}_X)\|_{\text{op}}^2} \right). \end{aligned}$$

Main Result: Simplified

$$B(r) \triangleq \left\{ f \in \mathcal{F}_* \mid \frac{1}{T} \sum_{t=0}^{T-1} \mathbf{E} \|f(X_t)\|_2^2 \leq r^2 \right\}, \quad \partial B(r) \triangleq \left\{ f \in \mathcal{F}_* \mid \frac{1}{T} \sum_{t=0}^{T-1} \mathbf{E} \|f(X_t)\|_2^2 = r^2 \right\}$$

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Then:

$$\mathbf{E} \|\hat{f} - f_*\|_{L^2}^2 \leq \underbrace{8 \mathbf{E} M_T(\mathcal{F}_*)}_{\text{"iid rate"}} + r^2 + B^2 \underbrace{|\mathcal{F}_r|}_{\lesssim \mathcal{N}_\infty(\mathcal{F}_*, r)} \exp\left(\frac{-T}{8C \|\Gamma_{\text{dep}}(P_X)\|_{\text{op}}^2}\right) \quad (13)$$

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choose $r^2 \asymp \mathbf{E} \mathbf{M}_T(\mathcal{F}_*)$

suppose $\|\Gamma_{\text{dep}}(P_X)\|_{\text{op}}^2 = O(1)$

$\mathcal{N}_\infty(\mathcal{F}_*, \mathbf{E} \mathbf{M}_T(\mathcal{F}_*))$ grows slower than the neg. exp. term 🟢

⇒ dominant term in (13) is $\mathbf{E} \mathbf{M}_T(\mathcal{F}_*)$

⇒ iid rate after a burn-in 🟢

Examples

Let's do some examples ☕

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Stable LDS

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Stable LDS

Stable and expansive GLM

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Stable LDS

Stable and expansive GLM

$\ell^2(\mathbb{N})$ -ellipsoids ("RKHS")

Example: Stable LDS

$$\text{LDS: } X_{t+1} = A_* X_t + H V_t, \quad X_0 = H V_0, \quad V_t \sim N(0, I)$$

¹Technically, we verify hyp.con. and mix. for a truncated noise process and then couple

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$$(A_*, H) \text{ } k\text{-step cont.}; \text{rank}([H \quad A_* H \quad A_*^2 H \quad \dots \quad A_*^{k-1} H]) = d_x$$

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$$\mathbf{E} \|(\hat{A} - A_*) \sqrt{\Sigma_X}\|_F^2 \lesssim \frac{\|H\|_{\text{op}}^2 d_X^2}{T} \quad (T \geq \text{poly}(\text{params}))$$

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relies on a bound from [Tu et al. \[2022\]](#) on the RHS of

$$\mathbf{E} M_T(\mathcal{F}_*) \leq \frac{4}{T} \mathbf{E} \left\| \left(\sum_{t=0}^{T-1} X_t X_t^T \right)^{-1/2} \sum_{t=0}^{T-1} X_t V_t^T H^T \right\|_F^2$$

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Use our main result + truncation:

$$\mathbf{E} \|\sigma(\hat{A}_\bullet) - \sigma(A_* \cdot)\|_{L^2}^2 \lesssim \frac{\|H\|_{\text{op}}^2 d_X^2}{T} \log \left(\max \left\{ T, B, d_X, \|P_*\|_{\text{op}}, \|H\|_{\text{op}}, \frac{1}{1 - \rho} \right\} \right)$$

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\Rightarrow ($C_{\text{GLM}}, 2$)-traj. hyp. with $C_{\text{GLM}} \lesssim \frac{B_X^4}{\sigma_{\min}(H)^4 \zeta^4}$ with

$$B_X = \frac{\|H\|_{\text{op}} \|P_*\|_{\text{op}}^{1/2} \sqrt{d_X}}{1 - \rho}$$

\Rightarrow can also control dependency matrix by stability

Use our main result + truncation:

$$\mathbf{E} \|\sigma(\hat{A}_*) - \sigma(A_* \cdot)\|_{L^2}^2 \lesssim \frac{\|H\|_{\text{op}}^2 d_X^2}{T} \log \left(\max \left\{ T, B, d_X, \|P_*\|_{\text{op}}, \|H\|_{\text{op}}, \frac{1}{1 - \rho} \right\} \right)$$

Compare [Kowshik et al. \[2021\]](#): $\|\hat{A} - A_*\|_F^2 = \tilde{O}(\|H\|_{\text{op}}^2 d_X^2 / (T \lambda_{\min}(\Sigma_X)))$

Example: Stable GLM

GLM: $X_{t+1} = \sigma(A_* X_t) + HV_t$, $X_0 = HV_0$, $V_t \sim N(0, I)$

$$\mathcal{F} \triangleq \{f(x) = \sigma(Ax) \mid A \in \mathbb{R}^{d_X \times d_X}, \|A\|_F \leq B\}$$

1-step-cont.; $H \in \mathbb{R}^{d_X \times d_X}$ is full rank

σ is 1-lip

σ is expansive; $\exists \zeta \in (0, 1] : |\sigma(x) - \sigma(y)| \geq \zeta|x - y|$ for all $x, y \in \mathbb{R}^{d_X}$

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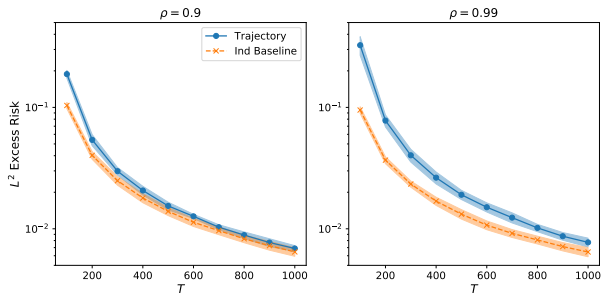
$$\mathbf{E} \|\sigma(\hat{A} \cdot) - \sigma(A_* \cdot)\|_{L^2}^2 \lesssim \frac{\|H\|_{\text{op}}^2 d_X^2}{T} \log \left(\max \left\{ T, B, d_X, \|P_*\|_{\text{op}}, \|H\|_{\text{op}}, \frac{1}{1 - \rho} \right\} \right)$$

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First up-to-logarithms rate-optimal excess risk bound 🟢

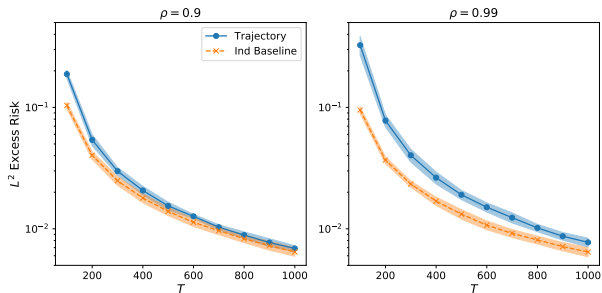
Example: Stable GLM, numerical experiment

LeakyReLU with slope 0.5, i.e., $\sigma(x) = 0.5\mathbf{1}\{x < 0\} + x\mathbf{1}\{x \geq 0\}$



Example: Stable GLM, numerical experiment

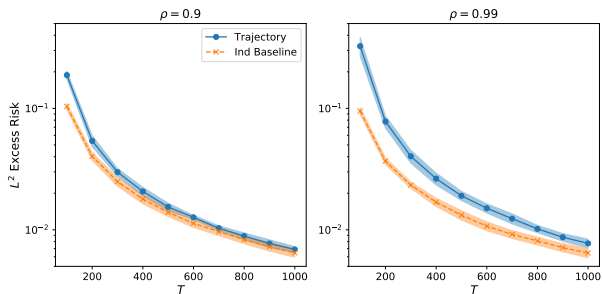
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L^2 excess risk as a function of dataset length T of ERM

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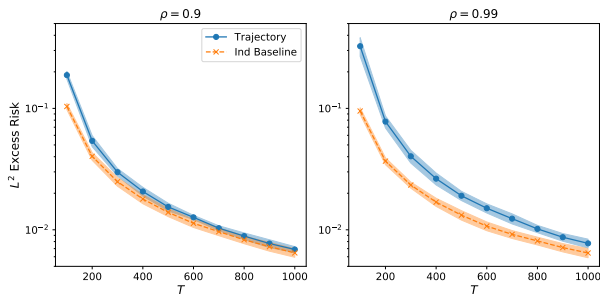


L^2 excess risk as a function of dataset length T of ERM

single trajectory (Trajectory) dataset versus independent baseline (Ind Baseline) dataset

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L^2 excess risk as a function of dataset length T of ERM

single trajectory (Trajectory) dataset versus independent baseline (Ind Baseline) dataset

independent baseline: same marginals but iid

Example: $\ell^2(\mathbb{N})$ -ellipsoids and hypercontractivity

Proposition

Fix $\beta, B, K, q, \varepsilon > 0$ and a base measure λ on X

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$$\mathcal{P} \triangleq \left\{ f = \sum_{j=1}^{\infty} \theta_j \phi_j \mid \sum_{j=1}^{\infty} \frac{\theta_j^2}{\mu_j} \leq 1 \right\}$$

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(P_ε, P_X) is $(C_\varepsilon, 2)$ -traj. hyp. with $C_\varepsilon = (1 + 7K^3 B^4 m_\varepsilon^{4q+2})$

$$\mathcal{P}_\star \triangleq \left\{ f = \sum_{j=1}^{\infty} \theta_j \phi_j \mid \sum_{j=1}^{\infty} \frac{\theta_j^2}{\mu_j} \leq 1 \right\} - \{f_\star\}$$

Under the hypotheses of the previous slide:

exponential eigenvalue decay

bounded ONS growth in $\|\cdot\|_\infty$

M.A.C. marginals

we get for $T \geq \text{poly}(\text{params})$:

$$\mathbf{E} \|\hat{f} - f_\star\|_{L^2}^2 \lesssim \mathbf{E} \mathbf{M}_T(\mathcal{P}_\star)$$

can bound $\mathbf{E} \mathbf{M}_T(\mathcal{P}_\star) = \tilde{O}(1/T)$ by chaining [[Ziemann et al., 2022](#)]

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Paper: <https://arxiv.org/abs/2206.08269>

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Nagaraj et al. [2020]: deflation unavoidable in the *worst case*

☞ Can do this with "classical" regularization but not with "modern"

Thanks for Listening

ziemann@kth.com

Bonus: an open problem

Consider LDS: $X_{t+1} = A_* X_t + W_t$

but assume A_* is known to be s -sparse

can invoke our main thm to obtain

$$\mathbb{E} \|\widehat{A} - A_*\|_{F, \Sigma_X}^2 = \tilde{O}\left(\frac{\sigma_W^2 s \log d}{T}\right)$$

not tractable (search over $\exp(s)$ ERM) 😞

Known results for LASSO on LDS are linear in the mixing time²

$$\|(\widehat{A} - A_*)\|_{F, \Sigma_X}^2 \lesssim \frac{t_{\text{mix}} \sigma_W^2 s \log d}{T}$$

tractable 😊

not minimax optimal 😞

Question: What is going on? Is there a trade-off between computation and statistical efficiency, or are existing analyses simply sub-optimal?

More open problems in our survey: [Tsiamis et al. \[2022b\]](#)

²Fattahi et al. [2019], Wainwright [2019], Lecué and Mendelson [2018]

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